

Brachystochrone

James Emery

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1 The Curve of Fastest Descent

We are to find the Brachystochrone curve, which is the path of fastest descent under gravity from one point to a lower point. Let a mass slide on a frictionless wire under the force of gravity. The path starts at $(0, 0)$ and ends at (x_f, y_f) . Energy conservation gives

$$\frac{1}{2}mv^2 = mgy,$$

where v is the velocity, m is the mass, and g is the acceleration of gravity.

Then

$$v = \sqrt{2gy}.$$

$$dt = \frac{ds}{v}$$

$$t = \int_0^{x_1} \frac{ds}{v} = \int_0^{x_1} \frac{\sqrt{1+y'^2} dx}{\sqrt{2gy}}.$$

The integrand is

$$F(x, y, y') = \frac{\sqrt{1 + y'^2} dx}{\sqrt{2gy}}.$$

From the calculus of variation, a necessary condition for a minimum time is that Euler's equation holds. Euler's equation is

$$\frac{\partial}{\partial x} \frac{\partial F}{\partial y'} - \frac{\partial F}{\partial y} = 0$$

$$\frac{\partial F}{\partial y'} = \frac{1}{\sqrt{2gy}} \frac{y'}{\sqrt{1 + y'^2}}$$

We have

$$\begin{aligned} \frac{d}{dx} (F - y' \frac{\partial F}{\partial y'}) &= \\ y' \frac{\partial F}{\partial y} + \frac{\partial F}{\partial y'} y'' - y'' \frac{\partial F}{\partial y'} - y' \frac{d}{dx} \frac{\partial F}{\partial y'} &= \\ y' \left(\frac{\partial F}{\partial y} - \frac{d}{dx} \frac{\partial F}{\partial y'} \right) &= 0. \end{aligned}$$

So

$$F - y' \frac{\partial F}{\partial y'} = c.$$

where c is a constant. Then

$$\frac{\sqrt{1 + y'^2}}{\sqrt{2gy}} - \frac{y' \cdot 2}{\sqrt{2gy}} \frac{1}{\sqrt{1 + y'^2}} = c.$$

Simplifying

$$1 = c \sqrt{2gy(1 + y'^2)}.$$

Squaring,

$$1 = c^2 (2gy(1 + y'^2)).$$

$$1/(c^2 2gy) - 1 = y'^2.$$

$$y'^2 = \frac{1 - 2c^2 gy}{2c^2 gy}.$$

So

$$\frac{dy}{dx} = \sqrt{\frac{k - y}{y}}$$

for some new constant k . Then

$$\begin{aligned} dx &= \frac{y}{\sqrt{ky - y^2}} dy. \\ x &= \int \frac{y}{\sqrt{ky - y^2}} dy. \\ &= -\sqrt{ky - y^2} + \frac{k}{2} \arccos\left(\frac{k - 2y}{k}\right) + M, \end{aligned}$$

where M is a constant. When $y = 0$, then $x = 0$, so M is zero. Let

$$\arccos(1 - (2y/k)) = \theta.$$

Then

$$\begin{aligned} y &= (k/2)(1 - \cos(\theta)). \\ x &= \frac{k}{2}(\theta - \sqrt{2(2y/k) - (2y/k)^2}) \\ &= \frac{k}{2}(\theta - \sqrt{1 - (1 - (2y/k))^2}) \\ &= \frac{k}{2}(\theta - \sqrt{1 - \cos^2(\theta)}) \\ &= \frac{k}{2}(\theta - \sin(\theta)) \end{aligned}$$

This is a cycloid, the curve generated by a point on a circle rolling on a line. The radius of the circle is $r = k/2$. Given x and y , then k and θ are determined by these two nonlinear equations. We may use Newton's method. The parametric equations of our cycloid are

$$x = r(\theta - \sin(\theta)),$$

and

$$y = r(1 - \cos(\theta)).$$

Suppose x and y are given, then dividing x by y , we get an equation

$$x/y = \frac{1 - \cos(\theta)}{\theta - \sin(\theta)},$$

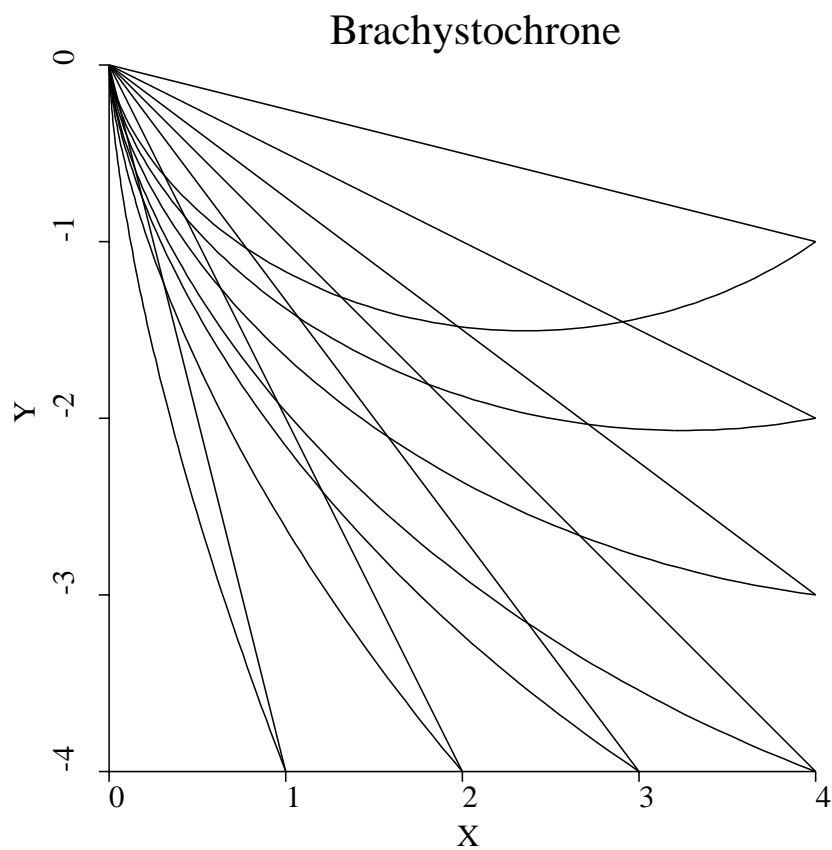


Figure 1: Cycloid curves of quickest descent, ending respectively at $(1,4)$, $(2,4)$, $(3,4)$, $(4,4)$, $(4,3)$, $(4,2)$, and $(4,1)$.

which may be solved numerically for θ . Solving for θ is equivalent to finding a zero of the function

$$f(\theta) = \frac{1 - \cos(\theta)}{\theta - \sin(\theta)} - \frac{x}{y}.$$

We have

$$\frac{df}{d\theta} = 1 - \frac{\theta - \sin^2(\theta)}{(1 - \cos(\theta))^2}.$$

We shall find the zero by using Newton's iteration. This is

$$\theta_{n+1} = \theta_n - \frac{f(\theta_n)}{f'(\theta_n)}.$$

We construct a Fortran program that reads a point (x_f, y_f) and finds an r , defining a cycloid that passes through the origin and point (x_f, y_f) . It also finds the angle parameter θ_f of (x_f, y_f) . Points on the cycloid are written to a file. These points may be plotted or imported to a CAD system using IGES (for original program on a unix machine).

The program given here is for a PC, using the Microsoft Fortran Power Station Compiler.

```

c      cycloid.ftn computes a cycloid curve starting at (0,0) and
c      ending at a specified point.  Written for Danielle H Kay in 1992
c      for a student demonstration.
c      Brachystochrone, see bra.tex
c original April 1992
c modified 4/3/2008,
c modified 11/7/2013
c There may be an original silicon graphics version different from this one somewhere.
      implicit real*8(a-h,o-z)
      dimension ain(5)
one=1
pi=4.*atan(one)
      open(2,file='p.eg',status='unknown')
      write(*,*)' See the document Brachistocrone, bra.pdf'
      write(*,*)' Writes curve points to p.eg '
      write(*,*)' The cycloid lies in the first quadrant,'
      write(*,*)' but is flipped when printed to p.eg '
      write(*,*)' so that the curves slope downward'
      write(*,*)' Use pltmerge to define plot window.'
      write(*,*)' pltmerge p.eg q.eg -w'
      write(*,*)' Use pltax to add axes and labels.'
      write(*,*)' pltax q.eg p.eg x y Cycloids '
      write(*,*)' Use eg2ps to make postscript file'
      write(*,*)' eg2ps p.eg p.ps'
      write(*,*)
      write(*,*)' Starting curve point is (0,0)'
      do
      write(*,*)' Enter the ending point of curve, x,y (x>0 y>0)'

```

```

write(*,*)' <return> to end. '
call readr(0,ain,nr)
if(nr .le. 0)exit
x=ain(1)
y=ain(2)
w = x/y
write(*,*)x, y
n = 20
t = w
if( w .gt. 6.d0) then
    t = 6
endif
if( w .lt. .01d0) then
    t = 1./100
endif
c   write(*,*)' t= ',t
do i = 1, n
c   write(*,*)' i= ',i
    f = (t - sin(t)) / (1 - cos(t)) - x / y
    a = 1 - cos(t)
    df = (a * a - (t - sin(t)) * sin(t)) / (a * a)
    t = t - f / df

    end do
write(*,*)'t=',t
r = y / (1 - cos(t))
write(*,*)' theta= ', t * 180. / pi, ' r= ', r
write(*,*)' x= ', x, ' cx=',r * (t - sin(t))
write(*,*)' y= ', y, ' cy=',r * (1 - cos(t))
g=9.81
tcd=sqrt(r/g)*t
write(*,*)' Time of descent on cycloid = ', tcd
tld=sqrt(2.*(x**2+y**2)/(y*g))
write(*,*)' Time of descent on line = ', tld
write(2,'(1x,a,2(1x,g15.8))')'m',0,0
write(2,'(1x,a,2(1x,g15.8))')'d',x,-y
n=100
do i=1,n
    tp=(i-1)*t/(n-1)
    if( i .eq. 1)then
        x=r*(tp -sin(tp))
        y=-r*(1.-cos(tp))
        write(2,'(1x,a,2(1x,g15.8))')'m',x,y
    else
        x=r*(tp -sin(tp))
        y=-r*(1.-cos(tp))
        write(2,'(1x,a,2(1x,g15.8))')'d',x,y
    endif
end do
end do
end
c+ readr read a row of floating point numbers
subroutine readr(nf, a, nr)
implicit real*8(a-h,o-z)
c numbers are separated by spaces
c examples of valid numbers are:
c 12.13 34 45e4 4.78e-6 4e2,5.6D-23,10000.d015

```

```

c  nf=file number, 0 for standard input file
c  a=array of returned numbers
c  nr=number of values in returned array,
c    or 0 for empty or blank line,
c    or -1 for end of file on unit nf.
c requires functions val and length
  dimension a(*)
  character*200 b
  character*200 c
  character*1 d
  c=' '
  if(nf.eq.0)then
    read(*,'(a)',end=99)b
  else
    read(nf,'(a)',end=99)b
  endif
  nr=0
  l=lenstr(b)
  if(l.ge.200)then
    write(*,*)' error in readr subroutine '
    write(*,*)' record is too long '
  endif
  do 1 i=1,l
    d=b(i:i)
    if (d.ne.' ') then
      k=lenstr(c)
      if (k.gt.0)then
        c=c(1:k)//d
      else
        c=d
      endif
    endif
    if( (d.eq.' ').or.(i.eq.l)) then
      if (c.ne.' ') then
        nr=nr+1
        call valsub(c,a(nr),ier)
        c=' '
      endif
    endif
1  continue
  return
99  nr=-1
  return
  end

c
c+ lenstr  nonblank length of string
  function lenstr(s)
c length of the substring of s obtained by deleting all
c trailing blanks from s. thus the length of a string
c containing only blanks will be 0.
  character s*(*)
  lenstr=0
  n=len(s)
  do 10 i=n,1,-1
  if(s(i:i).ne.' ')then
    lenstr=i
  return

```

```

        endif
10    continue
        return
        end
c+ valsub converts string to floating point number (r*8)
        subroutine valsub(s,v,ier)
        implicit real*8(a-h,o-z)
c     examples of valid strings are: 12.13 34 45e4 4.78e-6 4E2
c     the string is checked for valid characters,
c     but the string can still be invalid.
c     s-string
c     v-returned value
c     ier- 0 normal
c         1 if invalid character found, v returned 0
c
        logical p
        character s*(*),c*50,t*50,ch*15
        character z*1
        data ch/'1234567890+-.eE'/
        v=0.
        ier=1
        l=lenstr(s)
        if(l.eq.0)return
        p=.true.
        do 10 i=1,l
            z=s(i:i)
            if((z.eq.'D').or.(z.eq.'d'))then
                s(i:i)='e'
            endif
            p=p.and.(index(ch,s(i:i)).ne.0)
10    continue
        if(.not.p)return
        n=index(s,'.')
        if(n.eq.0)then
            n=index(s,'e')
            if(n.eq.0)n=index(s,'E')
            if(n.eq.0)n=index(s,'d')
            if(n.eq.0)n=index(s,'D')
            if(n.eq.0)then
                s=s(1:l)//'.'
            else
                t=s(n:1)
                s=s(1:(n-1))//'. '//t
            endif
            l=l+1
        endif
        write(c,'(a30)')s(1:l)
        read(c,'(g30.23)')v
        ier=0
        return
        end

```


2 The Time of Descent

We have

$$x = r(\theta - \sin(\theta)), y = r(1 - \cos(\theta)).$$

Then

$$\begin{aligned}\frac{dx}{d\theta} &= y, \\ dx &= yd\theta,\end{aligned}$$

and

$$y' = \frac{dy}{dx} = \frac{dy}{d\theta} \frac{d\theta}{dx} = \frac{r \sin(\theta)}{y} = \frac{\sin(\theta)}{1 - \cos(\theta)}.$$

Then the time of descent on the cycloid is

$$\begin{aligned}t &= \int_0^{\theta_f} \sqrt{\frac{1 + y'^2(\theta)}{2gy(\theta)}} y(\theta) d\theta \\ &= \int_0^{\theta_f} \sqrt{\frac{(1 + y'^2(\theta))y(\theta)}{2g}} d\theta.\end{aligned}$$

We have

$$\begin{aligned}yy'^2 &= r(1 - \cos(\theta)) \frac{\sin^2(\theta)}{(1 - \cos(\theta))^2} \\ &= r \frac{1 - \cos^2(\theta)}{1 - \cos(\theta)} = r(1 + \cos(\theta)).\end{aligned}$$

So the integrand becomes

$$\sqrt{\frac{r}{g}}.$$

The descent time is

$$t = \sqrt{\frac{r}{g}} \theta_f.$$

Let us now find the time of descent on a straight line path. The acceleration a , in the line direction, is constant. We have

$$a = \sin(\phi)g = \frac{y_f}{\sqrt{x_f^2 + y_f^2}}g,$$

where ϕ is the angle between the line and the horizontal. Then the distance traveled in time t along the line is

$$s = \frac{at^2}{2}.$$

We have

$$s = \sqrt{x_f^2 + y_f^2}.$$

Then the descent time is

$$t = \sqrt{\frac{2(x_f^2 + y_f^2)}{y_f g}}.$$

3 Run Example

I think the program was run on a Silicon Graphics Unix Workstation.

```
% ftn8 cycloid
no errors, no warnings, no informational messages,
Fortran 77 compiler 68K Rev 10.8(190) 1992/11/12 17:50:13 CDT (Thu)
All Globals are resolved.
% a.out
  writes points to p.cd
  enter point, <return> to end
2.2 1.2
2.2000000000000000 1.2000000000000000
  theta= 193.6277113332691 r= 0.6085664327313063
  x= 2.2000000000000000 2.2000000000000000
  y= 1.2000000000000000 1.2000000000000000
  time of cycloid descent = 0.8421429774116072 seconds
  time of line descent = 1.033454019724319 seconds
  write points?
y
```